

ENERGY RESOURCE OPTIMIZATION IN WIRELESS AD-HOC NETWORK USING DYNAMIC STATES

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ABSTRACT

Wireless Ad-hoc network is the decentralized type of network and it does not rely on pre-existing infrastructure. The Energy efficiency continues to be a key factor in limiting the deploy ability of ad-hoc networks. Deploying an energy efficient system exploiting the maximum life time of the network has remained a great challenge since years. The major concern in Wireless network in recent days is Energy consumption. There are numerous algorithms proposed to overcome this issue. In this paper, we proposed a algorithm called Energy Efficiency Dynamic State (EEDS) algorithm. This algorithm is designed to increase the network lifetime by continuously monitoring the individual nodes in the network, thereby it increases the quality of service of the network.

Index Terms---LEAD, Virtual grid, EEDS, Network lifetime, Dynamic states

I. INTRODUCTION

Network is the collection of nodes (computer systems) that can be connected through the communication link. The link can be wired or wireless. If the nodes are connected through the air or space, then it is called wireless network. Ad-hoc Network is Built for Special Purposes, It Does not rely on the Base Stations Or Routers. Wireless Ad-hoc network is not centralized and have structure which contains collection of nodes in specific range. Every individual node participating in routing to forward the data to other nodes. To improve the quality of service we need to improve mainly the 3 parameters that are, PDR (packet delivery Ratio) is the essential parameter to measure the network performance. PDR is defined as the Ratio between the total number of packets received to the total number of packets sent by the nodes. Throughput is the second essential parameter. In networks, throughput is defined as the amount of data can be sent by the source node per unit time (typically it can be measured by bits per second (bps)). Network Lifetime is the Most essential parameter to improve the performance of the network. It is the time taken by the node at which it starts participating in routing until the node running out of energy. While improving the above 3 parameters we should Avoid the Attacks to the nodes, Reduce the congestion and traffic and maintain the energy.

II. RELATED WORKS

Subhankarmishra [1] proposed the algorithm called LEAD that deals with the energy efficiency round scheduling of cluster head allocation of nodes. After that the ordinary nodes are allocated to the cluster heads for maximizing the network lifetime using ANDA algorithm.

Sumithradevi [2] proposed the ANDA algorithm which comprises two algorithm which are covering algorithm and reconfigure algorithm.

Singh [3] proposed Homogeneous Clustering Algorithm (HCA) the whole network is virtually divided into zones based on geographical layout and density of the

network and it ensures the uniform selection of cluster heads.

Sasikala [4] proposed HEED (Hybrid Energy Efficient Distributed) clustering method maximizes the network lifetime by distributing the energy consumptions and it creates well distributed cluster heads. HEED extends the scheme of LEACH.

Anantha Chandrakasan [5] proposed LEACH- Low Energy Adaptive Clustering Hierarchy. In LEACH it will randomly distributes the energy among the nodes in the network. The nodes in the network organize themselves as a local network and assign a cluster head. LEACH compress the data which is sent from the cluster heads to the BS. Hence it reduces the energy dissipation. So, it enhances the network lifetime.

Deosarkar [6] proposed the idea led to the construction of the sensor network as several clusters with a dynamically elected cluster-head node is only allowed to forward the data to the sink.

Xue [7] proposed a cellular-assisted UE CH selection algorithm for the WSN, which considers several parameters to choose the optimal UE gateway CH. They analyze the energy cost of data transmission from a sensor node to the next node or gateway and calculate the whole system energy cost for a WSN.

Lukachan [8] consider these issues in the design of a simple, scalable, energy-efficient location aided routing (SELAR) protocol for WSN. In SELAR, location and energy information of neighbouring nodes together with the location information of the sink node are used to perform the routing function.

Aslam [9] present a novel energy efficient cluster formation algorithm based on a multi-criterion optimization technique. Our technique can use multiple individual metrics in the cluster head selection process as input while simultaneously optimizing on the energy efficiency of the individual sensor nodes as well as the overall system.

Ergen [10] compare two multi-hop routing schemes: the first maximizes the minimum lifetime of the nodes; the second minimizes total energy consumption. We consider both the transmission energy and circuit energy spent in transmission, as well as the reception energy.

Qin [11] proposed a Replication strategy in peer-to-peer systems. In this only node that request an object make copies of the object.

Cohen [12] proposed two different replica strategies uniform and proportional - yield the same average performance on successful queries.

Giwon [13] proposed the dynamic replication for peer to peer networks. It mainly focused on tackle of replica placement problem.

TABLE I. INFERENCE OF RELATED WORKS

Proposed Method	Algorithm Used	Tools Used	Year of publication	Inference
Energy efficiency based on round scheduling of cluster head allocation of nodes	LEAD	NS-2	2011	This algorithm quite outperforms the traditional energy efficient algorithms by 35%
Energy Efficiency Based on Homogeneous clusters	HCA	NS-2	2010	The life span of the network is increased by ensuring a homogeneous distribution of nodes in the clusters
Search and Replication in Unstructured Peer-to-Peer Networks	Gnutella's query algorithm	GloMoSim	2002	It can find data reasonably quickly while reducing the network traffic
QoS-Controlled Dynamic Replication in Peer-to-Peer Systems	Replica Placement Algorithms	GloMoSim	2002	It tackled the replica placement problem and studied the effects of the number and location of replicas on the reached QoS

III. PROPOSED METHODOLOGY

A. Simulation

1) Network Formation:

Simulation is regulated using NS2 2.35. Because of the link stability and route lifetime, no route overhead was considered in our simulation. In 500 X 500 area, mobile nodes exist. Square area is used to increase average hop length of a route with relatively small nodes. Every mobile node is moving based on the mobility data files that were generated by mobility generator module. Several 50 nodes is created. The transmission range is fixed at 100 meters. 100 nodes have destinations and try finding routes to their destination nodes. Maximum speed of node is set to 20 m/sec. The nodes are assigned with an initial position. All nodes do not stop moving and the simulation second is 500 seconds.

```
# configure node
$ns_ node-config -adhocRouting $val(rp) \
-llType $val(ll) \
-macType $val(mac) \
-iftType $val(ift) \
-iftLen $val(iftlen) \
-antType $val(ant) \
-propType $val(prop) \
-phyType $val(netif) \
-channelType $val(chan) \
-topoInstance $topo \
-agentTrace ON \
-routerTrace ON \
-macTrace OFF \
-movementTrace OFF \
-energyModel $val(energyModel) \
-initialEnergy $val(initialEnergy) \
-rxPower 35.28e-3 \
-txPower 31.32e-3 \
-idlePower 712e-6 \
-sleepPower 144e-9
```

Fig. 1. Initialization of Nodes

In this section, we describe the EEDS algorithm. Initially, the network is divided into virtual grids. Each virtual grid is assigned with n number of nodes based on their current position. The nodes which are in the same virtual grid are designed in such a way that these nodes within a grid will rely on one another i.e., any node in the virtual grid can assign its work to the any other node which is present in the same virtual grid.

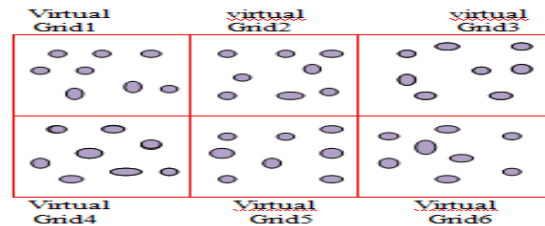


Fig. 2. Representation of Virtual Grids of the Network

In this paper, we discuss about three different states where a node can enter to conserve its energy. i) Active state –it contains the nodes which is actively participating in the routing process. ii) Night mode - it contains the nodes which are idle and it is in a energy consuming state. iii) Discovery state- it contains nodes which are ready to participate in routing process.



Fig. 3. Representation of States of the Node.

Let us consider the node in active state which is participating in routing. Initially the energy of the node is considered cent percent. During the process of routing, the energy of the node will be consumed for every transmission and reception of packets. Once the simulation is started the nodes which involve in packet transfer will lose energy. When a node's energy is consumed up to 10%, then the node is moved to night mode state where the node is idle for a certain timestamp. In this mode, the node will be idle or inactive and consumes its energy so that it can be active in the network more than a stipulated time. In this state the node's energy will remain constant as it does not involve in any kind of process. The buffer size of each state is set to 5. This implies that any state can accommodate 4 nodes simultaneously since a free space should be

allocated for a new node entering the state. When the fifth node enters the buffer, the first node that entered the buffer will move towards the discovery state indicating that it is ready to actively participate in the routing process.

In discovery state, the node consumes half of the energy when compared to the energy consumed by the active state since it triggers an alarm periodically indicating that it is ready to enter the active state. The node triggers an alarm when it is in a discovery state for a time stamp greater than T.

Similarly, when a node in active state loses 10 percent of its energy and wants to move to the night mode, it send a request message to discovery state for a node to enter the active state. This process continues although the simulation for efficient energy management of each node in the network which in turn increases the overall network lifetime. As discussed earlier, the nodes in the virtual grid are mutual to each other, when one node enters the night mode, it assigns its work to the neighbouring node in the same virtual grid. Consider the following routing process which denotes the shortest path form source (a) to destination (h).

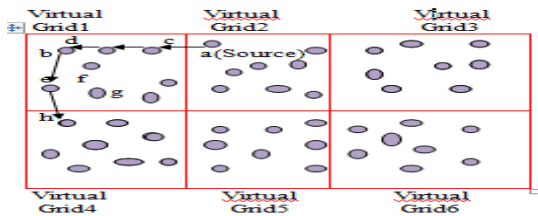


Fig. 4. Actual Shortest Path from Source to Destination.

The above figure shows the source and destination nodes named as a and h respectively. The intermediate nodes are b, c, d and e. The packets are transferred from a to h through b, c, d and e. Here, the nodes d and e consumed 10% of energy and so these two nodes are ready to enter into the night mode to conserve its energy.

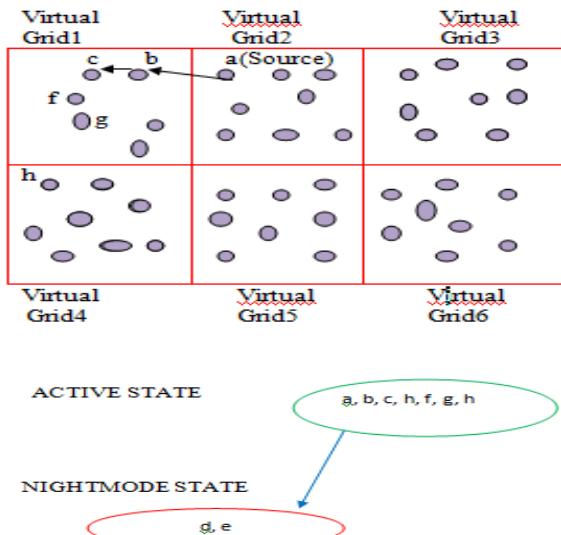


Fig. 5. Representation of Nodes in Night Mode State.

The above figure represents the nodes d and e are in the night mode state and it does not consumes energy and remains the same until it enters into the discovery state.

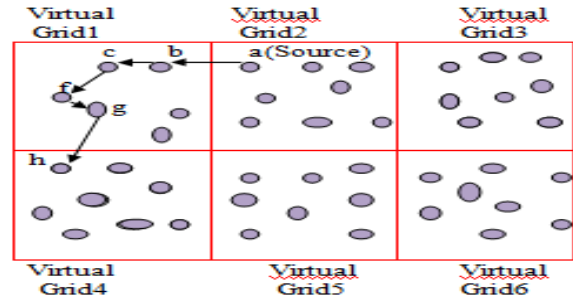


Fig. 6. Representation of the Node Assigning its Work to its Neighbouring Nodes.

The above figure represents the nodes d and e assigns their work to the neighbouring nodes f and g respectively. Hence in the routing process nodes f and g participate on behalf of nodes d and e respectively. Assigning a node work to some other is done by duplicating its id whenever necessary.

```

1005 Packet Transmission Routines
1006 */
1007
1008 void
1009 AODV::forward(aodv_rt_entry *rt, Packet *p, double delay) {
1010 struct hdr_cmn *ch = HDR_CMN(p);
1011 struct hdr_ip *ih = HDR_IP(p);
1012 //****Code to print Node position and Energy: Mano]
1013 iNode = (MobileNode *) (Node::get_node_by_address(index));
1014 xpos = iNode->X();
1015 ypos = iNode->Y();
1016 iEnergy = iNode->energy_model()->energy();
1017 printf("at Time (%.6f), Position of %d is X: %.4f and Y: %.4f \n", CURRENT_TIME, index, xpos, ypos);
1018 printf("at Time (%.6f): Updated Energy for Node %d is Energy %.4f \n", CURRENT_TIME, index, iEnergy);
1019 //*****
1020
1021 if(ih->ttl_ == 0) {
1022
1023 #ifdef DEBUG
1024 fprintf(stderr, "%s: calling drop()\n", __PRETTY_FUNCTION__);
1025 #endif // DEBUG

```

Fig. 7. Code to Print Position and Energy

B. Flow Chart

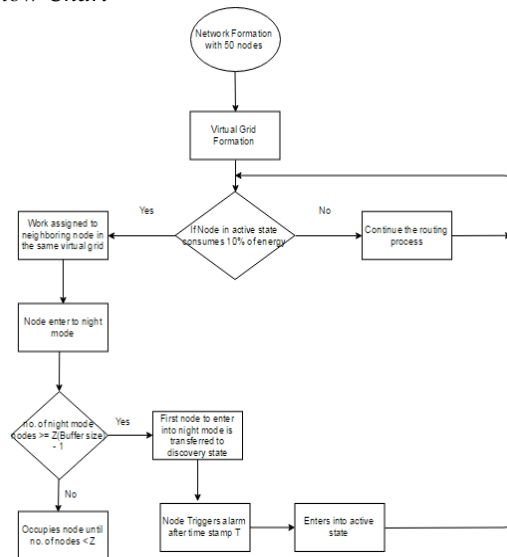


Fig. 8. Energy Efficient Dynamic State Algorithm

C. EEDS Algorithm

```

INPUT: N nodes with 100% of energy
Z- Buffer Size, T- Time Stamp
1. Initialize n nodes to the network
2. Form the virtual grids
3. IF node losses 10% energy
4.   Assign its work to its neighboring node
5.   Node enters into night mode
6.   IF No. of nodes in the night mode >= z - 1
7.     First node is transferred to the discovery state
8.     IF node in the discovery state exceeds timestamp T
9.       Node triggers the alarm
10.      Enter into the active state
11.   ELSE
12.     Occupy the buffer until the No. of nodes < z
13.   ENDIF
14. ELSE
15.   Continue the routing Process.
16. ENDIF
    
```

Fig. 9. Energy Efficient Dynamic State(EEDS)

This algorithm is found to be more efficient than existing algorithms since entire network lifetime is maintained uptime throughout the simulation

IV. EXPERIMENTAL ANALYSIS

The packets are routed very efficiently by nodes that are actively participating in the routing process. The Packet Loss Ratio is evaluated with the parameters such as number of packets sent and number of packets received. It is inferred that as the number of nodes with minimum energy increases with respect to the simulation time the packet loss ratio increases gradually as shown in the Figure 10. The Calculated packet loss ratio is lesser than the value that obtained without any Energy efficiency algorithm incorporated in nodes in the network.

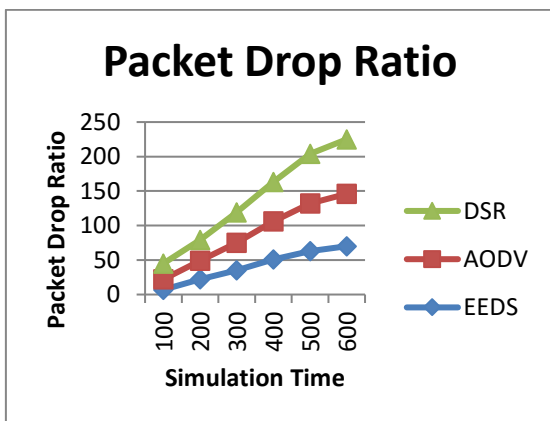


Fig. 10. Packet Drop Ratio Comparison between AODV, OLSR and EEDS

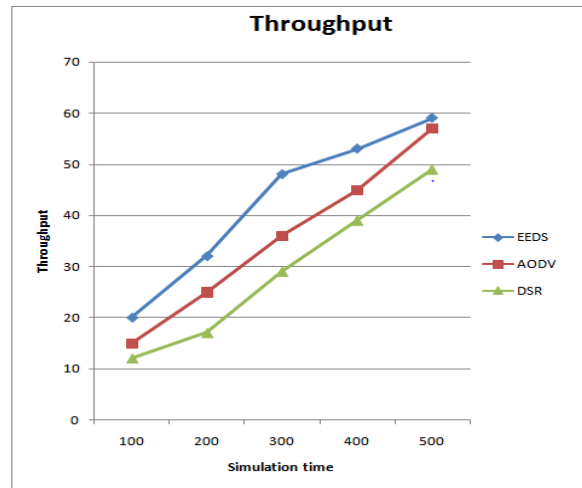


Fig. 11. Throughput Comparison between EEDS, AODV and DSR.

From the above graph, it is inferred that once the Energy Efficiency Dynamic State Algorithm has been incorporated with the routing protocol the results produced are far better than the other traditional methods used for energy efficiency. Here the Packet Drop Ratio is tremendously reduced when each node in the network can actively participate in transmitting and receiving the packets beyond a stipulated timestamp. Similarly, the obtained results for throughput also infers that results are better than other existing works. EEDS Algorithm has been compared with other routing protocols for comparison.

In the below table, the nodes lifetime is compared with respect to simulation time. The results obtained are more encouraging that above 80 percentage of the nodes maintain its energy level above 50 Percentage after the end of simulation. This shows that the entire network can perform more than an expected time stamp with uptime efficiency.

TABLE II. Comparison of active nodes with respect to simulation time

Simulation Time	No. of nodes > 50 percent energy level
100	50
200	49
300	47
400	43
500	41

```

for (set i 0) { $i < $val(nn) } { incr i } {
set CE($i) [expr $InitialEnergy($i) - $FinalEnergy($i)]
puts $en "Energy consumption($i) = $CE($i)"
}
set energyConsumption 0
for (set i 0) { $i < $val(nn) } { incr i } {
set energyConsumption [expr $CE($i) + $energyConsumption]
}

```

Fig. 12. Computation of Energy Level After Simulation

V. CONSLUSION

Network lifetime is considered to be the major impact that influences the performance of the network. This Paper Proposed a solution to improve the entire lifetime of the network by monitoring the nodes continuously. The Energy Efficiency Dynamic State Algorithm enhances the nodes performance throughout the simulation by maintaining the energy of the node uptime than other traditional methods used to provide energy efficiency. Since all the nodes can actively perform in the routing process beyond the expected timestamp the overall performance is also increased. Our future work will be implementing this algorithm that can sustain the attacks and still maintain the same quality of service.

VI. REFERENCES

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